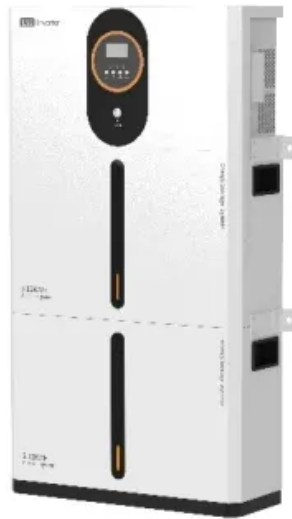


SolarInvert Energy Solutions

Jimu Battery Inverter



Overview

How does a Jimu robot work?

The brain of a Jimu robot is a Main control box. Once the mobile phone has connected over wireless to the main control box, it can be used to control the Jimu robot. There is an exclusive 1.Main Control Box MAC address for the controller on its back. The battery comes factory-installed on the main control box. You can also replace the battery.

How do I connect the Jimu robot to the control box?

Power allows the Jimu robot to operate. Use the connecting cable to connect the 6.Power Switch power switch to the Main control box. Turn on/off the power using the power switch. 7.Decorating Piece - Fasteners Fasteners can integrate decorating pieces, connectors, the controller, and servos together through holes.

What connectors does Jimu use?

The first thing to notice, even before we open the case is that Jimu uses the same 3 pin connectors as Robotis XL-320 series (used in the MINI series) - specifically MOLEX Micro Latch 53254. The iPad application seems to be very insistent to make sure that the cables from servos are connected to the controller to the correct port number.

Is the Jimu module suitable for mobile devices?

This is a 3.0 / 4.0 + EDR module, as mentioned also in the Jimu documentation, very suitable for today's mobile devices. It's also nice to see that each 3-pin servo bus connector is nicely decoupled with a 100µF capacitor.

How do you connect a servo to a Jimu robot?

Example: Connecting Servo with C3 Straighten the rudder and Gently widen both sides align the component. of the component. Push the right side of the

Adjust the other side. Power allows the Jimu robot to operate. Use the connecting cable to connect the 6.Power Switch power switch to the Main control box.

How do I adjust a Jimu robot?

"Record movement" icon A Record Movement icon will appear on the movement axis after the Jimu robot is connected. Click the icon and the Jimu robot will automatically loosen the joint. You can now adjust the robot into the posture you want. Click the icon again and the posture will be added to the movement axis.

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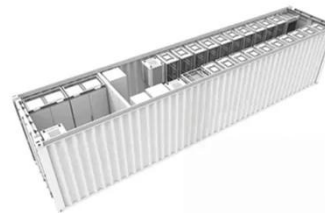
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